Contents

Chapter Wise all semester Final & Mid Ques Solved!

Note: ২ ঘন্টায় যতটুকু পারার ট্রাই করছি। বাট Chapter 6, 21,22,23,32 বেশি important আমার কাছে মনে হয়।

Chapter 1 & 3

18-19 mid1

1(a) . What do you mean by datatype? Is Array a data structure? Justify your answer.

A datatype is a classification of data that determines the type of operations that can be performed on it. In programming, data types are used to define variables, functions, and parameters in a program.

An array is a data structure that stores a collection of elements of the same data type in contiguous memory locations. As such, it is not a data type but a data structure that uses a specific data type to store its elements.

Arrays are a fundamental data structure in programming and are used to store and manipulate collections of data efficiently. They allow for quick access to individual elements and support operations such as sorting and searching.

Arrays also support dynamic resizing, making them versatile for handling collections of varying sizes. They are commonly used in algorithms, data processing, and database management.

In summary, while arrays are not a data type, they are a crucial data structure that relies on a specific data type to store its elements.

18-19 mid1

1(b) .What do you mean by random-access machine?

A random-access machine (RAM) is a theoretical model of computation that performs calculations on a stored program. It is a type of computer architecture that allows for constant-time access to any memory location, irrespective of the memory's physical location.

The RAM model assumes that every operation takes the same amount of time, and its performance is typically measured in terms of the number of basic operations performed.

The RAM model is used to analyze the time and space complexity of algorithms, and it is a widely used theoretical framework for studying computation.

17-18 final

1(a). Write down the definitions of algorithms as technology.

An algorithm is a set of instructions or rules that a computer program follows to accomplish a task. It is a sequence of steps that a computer executes to solve a problem.

Algorithms are considered a technology because they enable the creation of software applications that can automate complex tasks. They provide a systematic and efficient

approach to solving problems, which is critical for developing software systems that can

handle large volumes of data.

Algorithms can be designed to perform a wide range of functions, from sorting and

searching data to processing images and speech. They are a key component of artificial

intelligence and machine learning, which rely on complex algorithms to analyze and learn

from data.

Algorithms are also used in a variety of industries, including finance, healthcare, and

transportation, to optimize resource usage, improve efficiency, and reduce costs.

In summary, algorithms are a technology that enables the development of powerful software

applications that can automate complex tasks, analyze data, and make intelligent decisions.

16-17 final

1(a). Why are data structures and algorithms so important in Computer science?

They provide a way to organize and manipulate data efficiently.

They help optimize resource usage, such as memory and processing power.

They are fundamental building blocks for developing complex software systems.

They enable software engineers to solve complex problems in a systematic and structured

way.

They improve the performance and scalability of software systems.

They are widely used in industries such as finance, healthcare, and transportation.

They are a critical component of coding interviews for tech jobs.

Mastery of data structures and algorithms is a hallmark of a competent software engineer.

8(a). Define algorithms and Data structures? As a CSE student, why should you have good knowledge on algorithms?

An algorithm is a set of instructions or rules that a computer program follows to accomplish a task. It is a sequence of steps that a computer executes to solve a problem. A data structure, on the other hand, is a way of organizing and storing data in a computer program, so it can be accessed and used efficiently.

As a computer science engineering (CSE) student, having good knowledge of algorithms is essential because algorithms are the building blocks of software systems. They enable you to develop efficient and effective solutions to complex problems and help optimize resource usage, such as memory and processing power.

Data structures, on the other hand, provide a way to organize and manipulate data efficiently, which is critical for developing complex software systems. Understanding different data structures and their operations can help you choose the right one for a given problem and develop software that performs optimally.

Overall, good knowledge of algorithms and data structures is essential for CSE students as it is critical to developing high-quality software and solving complex problems efficiently. It is a fundamental component of computer science and is widely used in industry and research.

Chapter 4

For a better understanding of TOH & LCS You can see the videos which I provide below:

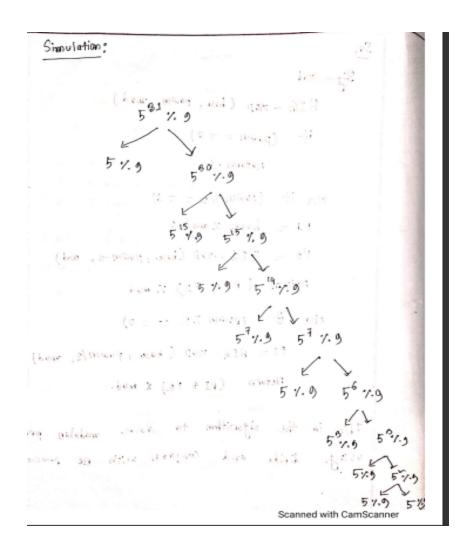
For TOH: Tower of Hanoi Problem - Made Easy

For LCS: LCS - Longest Common Subsequence - Algorithms (Bangla Tutorial)

Big mod er link:

https://imranshabijabi.wordpress.com/2012/11/24/%E0%A6%AC%E0%A6%BF%E0%A6%97-%E0%A6%AE%E0%A7%8B%E0%A6%A1-%E0%A6%85%E0%A7%8D%E0%A6%AF%E0%A6%BE%E0%A6%B2%E0%A6%97%E0%A7%8B%E0%A6%B0%E0%A6%BF%E0%A6%A6%E0%A6%AEbig-mod-algorithm/

Ques and Ans part:



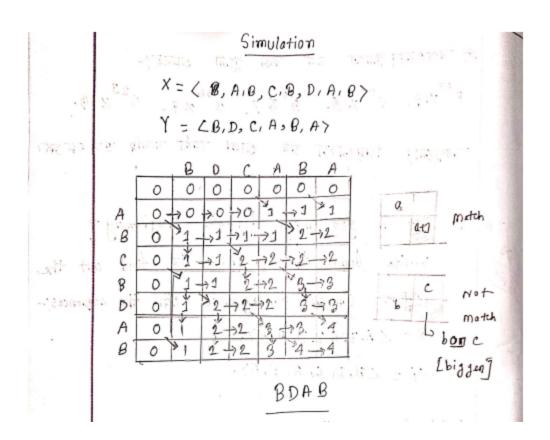
* বিপত বছৰ পুনতে তম সাম পুনো আমেছে:
5 ° 7 · 7 , 7 ° 7 ° 9 , 0 ° 7 , 3 ° 7 , 3 ° 7 , 9 ° 7

1.05 Topic What do you mean dynamic Programing?

Write down the program to find out the longest common Subsequence on the sequences:
X = < A.B., C.B., D. A.B.>.

Y = < B.D. C. A.B.A.>.

Sola: Dynamic Programing: Dynamic Programing like the divide and conquer method, solves problems by combining combining the solutions to subproblems.



TOH:

O: Write down the reconsive formula for B disks of the "Tower of Hamoi" problems

Solon The Hower of hanoi consists of three rods and a number of disks of different periods meters.

If there are n disk we write:

TOH (n, A, B, C)If n = 0Toh (n-1, A, C, B)Print $(A \rightarrow C)$ Toh (n-4, B) A = C

Here, is 7 moves for 3 disk:
10te: पारकामा अपू पिएम एवं उद्धा 3 disks एवं मामणाम

2 disks पिएम एकरें जारम। पूर्व आरम लाउदेव

पर्दाण लागाम ती। विशय वहबुश्लास्य एवं अपूरे क्वुस्

नाव्यावः मि

Chapter 6

To learn Heap Sort: 2.6.3 Heap - Heap Sort - Heapify - Priority Queues

18-19 mid-1

2(b) . Write down the algorithm of Heap sort with example. [4]

```
Heapsort(A)
```

- BUILD-MAX-HEAP(A)
- 2 for i = A.length downto 2
- 3 exchange A[1] with A[i]
- 4 A.heap-size = A.heap-size 1
- 5 MAX-HEAPIFY (A, 1)

Example .###17-18 final Data structure 2(c) as same

18-19 mid-1

2(c). Write pseudo code for the procedures HEAP_DECREASE_KEY that implements a min priority queue with a min-heap

 (CLRS 6.5-3) Write pseudocode for the procedures HEAP-EXTRACT-MIN, HEAP-DECREASE-KEY and HEAP-INSERT that implement a min-priority queue with a min-heap.

Solution:

```
HEAP-MINIMUM(A)
  return A[1]

HEAP-EXTRACT-MIN(A)
  if heap-size[A] < 1
    then error ''heap underflow''
  min <- A[1]
  A[1] <- A[heap-size[A]]
  heap-size[A] <- heap-size[A] - 1
  MIN-HEAPIFY(A,1)
  return min</pre>
```

```
HEAP-DECREASE-KEY(A,i,key)
  if key > A[i]
    then error ''new key is larger than current key''
  A[i] <- key
  while i > 1 and A[parent(i)] > A[i]
    do exchange A[i] <-> A[parent(i)]
    i <- parent(i)

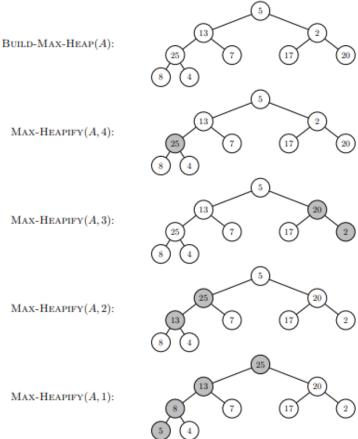
MIN-HEAP-INSERT(A,key)
  heap-size[A] <- heap-size[A] + 1
  A[heap-size[A]] <- +inf
  HEAP-DECREASE-KEY(A,heap-size[A],key)</pre>
```

17-18 final

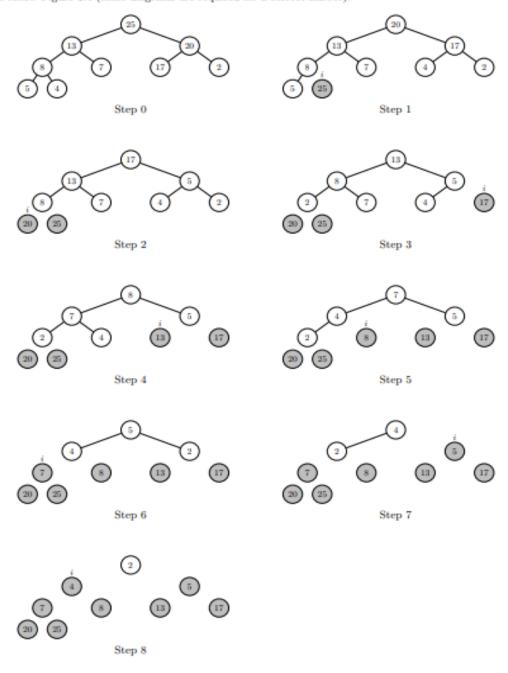
2(c). Write down the operation of HEAPSORT on the array A = < 5, 13, 2, 25, 7, 17, 20, 8, 4>

6.4-1 (p.160) Using Figure 6.4 as a model, illustrate the operation of Heapsort on the array A = (5, 13, 2, 25, 7, 17, 20, 8, 4).

Since A.length = 9, the command Max-Heapify(A, i) is called for i = 4, 3, 2, 1. The action of Build-Max-Heap is as follows (these first few diagrams are not required for a correct answer), with the nodes exchanged at each step shaded:



Now we follow Figure 6.4 (these diagrams are required for a correct answer):



This gives a final sorted array A = (2, 4, 5, 7, 8, 13, 17, 20, 25).

16-17 final

1(c). What do you mean by priority queue? Write down the operations of the priority queue? Write down the program to max heapify of an array?

A priority queue is a type of data structure that stores a collection of elements with associated priorities. Each element in the queue is assigned a priority, and the queue maintains the order of the elements based on their priority.

The operations of a priority queue are:

Insertion: Add an element to the queue with its associated priority. Deletion: Remove the element from the queue with the highest priority. Peek: Get the element with the highest priority without removing it from the queue.

Change Priority: Modify the priority of an element already in the queue. Merge: Combine two priority queues into a single queue while maintaining the order of the elements based on their priorities.

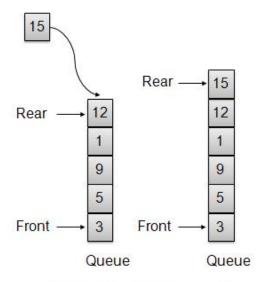
Priority queues are commonly used in algorithms such as Dijkstra's shortest path algorithm and Huffman coding. They are also used in computer networking, operating systems, and other applications where scheduling or resource allocation is required.

Operations

- · A max-priority queue provides the following operations:
 - o insert: add an element to the priority queue.
 - maxElement: return the largest element in the priority queue.
 - removeMaxElement: remove the largest element from the priority queue.

Insert / Enqueue Operation

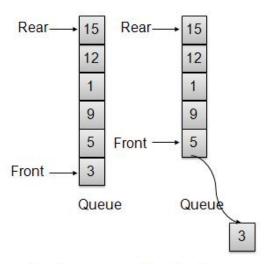
Whenever an element is inserted into queue, priority queue inserts the item according to its order. Here we're assuming that data with high value has low priority.



One item inserted at rear end

Remove / Dequeue Operation

Whenever an element is to be removed from queue, queue get the element using item count. Once element is removed. Item count is reduced by one.



One Item removed from front

**code:

https://www.geeksforgeeks.org/building-heap-from-array/

```
// C++ program for building Heap from Array
#include <iostream>
using namespace std;

// To heapify a subtree rooted with node i which is
// an index in arr[]. N is size of heap
void heapify(int arr[], int n, int i)
{
    int largest = i; // Initialize largest as root
    int I = 2 * i + 1; // left = 2*i + 1
    int r = 2 * i + 2; // right = 2*i + 2
```

```
// If left child is larger than root
       if (I < n && arr[I] > arr[largest])
              largest = I;
      // If right child is larger than largest so far
       if (r < n \&\& arr[r] > arr[largest])
              largest = r;
      // If largest is not root
       if (largest != i) {
              swap(arr[i], arr[largest]);
              // Recursively heapify the affected sub-tree
              heapify(arr, n, largest);
       }
}
// Function to build a Max-Heap from the given array
void buildHeap(int arr[], int n)
       // Index of last non-leaf node
       int startldx = (n / 2) - 1;
       // Perform reverse level order traversal
      // from last non-leaf node and heapify
       // each node
      for (int i = startIdx; i \ge 0; i--) {
              heapify(arr, n, i);
       }
}
// A utility function to print the array
// representation of Heap
void printHeap(int arr[], int n)
       cout << "Array representation of Heap is:\n";</pre>
```

```
for (int i = 0; i < n; ++i)
             cout << arr[i] << " ";
      cout << "\n";
}
// Driver Code
int main()
{
      // Binary Tree Representation
      // of input array
      //
                                   1
      //
      //
                     3
                                   5
      //
              /\
                     /\
      //
              4
                     6 13 10
      ///\/
      //
              9 8 15 17
       int arr[] = { 1, 3, 5, 4, 6, 13, 10, 9, 8, 15, 17 };
      int n = sizeof(arr) / sizeof(arr[0]);
       buildHeap(arr, n);
       printHeap(arr, n);
      // Final Heap:
      //
                                   17
      //
                     /
                            \
                            15
                                          13
      //
      //
              /\
                     /\
      //
                     9
                            6 5 10
      //
              /\/\
              4831
      //
       return 0;
}
```

16-17 final 2(c) er ii & 17-18 final 2(c)

17-18 final algorithm 2(c):

Write down the procedure of HEAP-MINIMUM and HEAP-EXTRACT-MIN Sol: Same as 18-19 mid-1 er 2(c)

17-18 final algorithm 2(d):

A heap is an advanced tree-based data structure used primarily for sorting and implementing priority queues. They are complete binary trees

Same as 17-18 final 2(c)

Chapter 7 & 8

Quick sort: 2.8.1 QuickSort Algorithm

Counting Sort: Counting Sort | Easiest explanation with example

Chapter 10

2016-17

[1.c] What do u mean by priority queue? Write down the operation of of the priority queue.[...........]

Solution:

The **priority queue in the data structure** is an extension of the "normal" queue. It is an abstract data type that contains a group of items. It is like the "normal" queue except that the dequeuing elements follow a priority order. The priority order dequeues those items first that have the highest priority.

It is an abstract data type that provides a way to maintain the dataset. The "normal" queue follows a pattern of first-in-first-out. It dequeues elements in the same order followed at the time of insertion operation. However, the element order in a priority queue depends on the element's priority in that queue. The priority queue moves the highest priority elements at the beginning of the priority queue and the lowest priority elements at the back of the priority queue.

Operation:

A priority queue is of two types:

- Ascending Order Priority Queue
- Descending Order Priority Queue

Ascending Order Priority Queue

An ascending order priority queue gives the highest priority to the lower number in that queue. For example, you have six numbers in the priority queue that are 4, 8, 12, 45, 35, 20. Firstly, you will arrange these numbers in ascending order. The new list is as follows: 4, 8, 12, 20, 35, 45. In this list, 4 is the smallest number. Hence, the ascending order priority queue treats number 4 as the highest priority.

4	8	12	20	35	45

In the above table, 4 has the highest priority, and 45 has the lowest priority.

Descending Order Priority Queue

A descending order priority queue gives the highest priority to the highest number in that queue. For example, you have six numbers in the priority queue that are 4, 8, 12, 45, 35, 20. Firstly, you will arrange these numbers in ascending order. The new list is as

follows: 45, 35, 20, 12, 8, 4. In this list, 45 is the highest number. Hence, the descending order priority queue treats number 45 as the highest priority.

45 35 20	12	8	4
----------	----	---	---

In the above table, 4 has the lowest priority, and 45 has the highest priority.

[3.a] Describe a situation where storing items in an array is clearly better than storing items on a linked list.

Solution:

When elements must be retrieved by their position.

[For more info]

Disadvantages of using linked lists over arrays-

- The main disadvantage of linked list over array is access time to individual elements. Array is random-access, which means it takes o(1) to access any element in the array. Linked list takes O(n) for access to an element in the list in the worst case.
- Another advantage of arrays in access time is special locality in memory. Arrays
 are defined as contiguous blocks of memory, and so any element will be
 physically near its neighbours. This greatly benifits from modern CPU caching
 methods.
- In linked list, Random access is not allowed. We have to access elements sequentially starting from the first node. So we cannot do binary search with linked lists.
- Extra memory space for a pointer is required with each element of the list. Hence Linked lists wastes memory in terms of extra reference points.

b) write down the output of this code with THREE pushs ONE pop
intStack s = new intStack();
s.push(1);
s.push(2);

s.push(3); s.push(12); s.push(14); print(s.pop()) C.write down the process of ENQUE and DEQUE usong an array.

Solution:

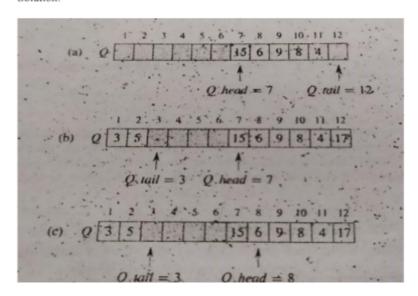


Figure 10.2 A queue implemented using an array Q[1...12]. Queue elements appear only in the lightly shaded positions. (a) The queue has 5 elements, in locations Q[7...11]. (b) The configuration of the queue after the calls ENQUEUE(Q.17), ENQUEUE(Q.3), and ENQUEUE(Q.5). (c) The configuration of the queue after the call DEQUEUE(Q) returns the key value 15 formerly at the head of the queue. The new head has key 6:

d. Draw a picture of the sequence 13,4,8,19,5,11 stored as a doibly linked list using the multiple array representation. Do the same for the single array representation

2017-18

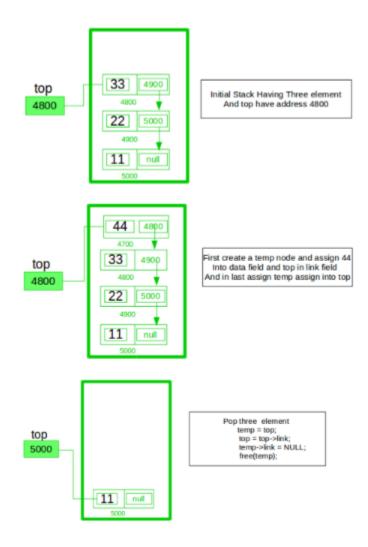
3

- c) Define Stack and Queue. Given the following numbers 10, 4, 6, 8.9 and 3, write
 - i) What would be the value to the stack, if three times push, one time pop, one time push and one time pop. Where push and pop operation refers to insert and pull an element to the stack respectively.
 - ii) What would be the value to the queue, if two times enqueue, one time dequcue, three times enqueue and four times dequeue.
 - iii) Write down the operations for making empty stack to the numbers.

d) Define linked list. Implement a stack using a singly linked list L The operations PUSH and POP should still take O(1) time.

Solution:

Implement a stack using single linked list concept. all the single linked list operations perform based on Stack operations LIFO(last in first out) and with the help of that knowledge we are going to implement a stack using single linked list. using single linked lists so how to implement here it is linked list means what we are storing the information in the form of nodes and we need to follow the stack rules and we need to implement using single linked list nodes so what are the rules we need to follow in the implementation of a stack a simple rule that is last in first out and all the operations we should perform so with the help of a top variable only with the help of top variables are how to insert the elements let's see



A stack can be easily implemented through the linked list. In stack Implementation, a stack contains a top pointer, which is "head" of the stack where pushing and popping items happens at the head of the list, first node have null in link field and second node link have first node address in link field and so on and last node address in "top" pointer.

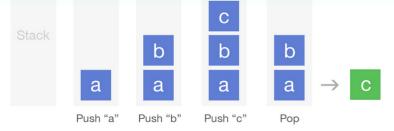
The main advantage of using linked list over an arrays is that it is possible to implements a stack that can shrink or grow as much as needed. In using array will put a restriction to the maximum

capacity of the array which can lead to stack overflow. Here each new node will be dynamically allocate, so overflow is not possible.

Stack Operations:

- push(): Insert the element into linked list nothing but which is the top node of Stack.
- pop(): Return top element from the Stack and move the top pointer to the second node of linked list or Stack.

Write down the implementation of a Queue using two Stacks.



Algorithm for queue using two stacks

For example: Suppose we push "a", "b, "c" to a stack. If we are trying to implement a queue and we call the **dequeue** method 3 times, we actually want the elements to come out in the order: "a", "b, "c", which is in the opposite order they would come out if we popped from the stack. So, basically, we need to access the elements in the reverse order that they exist in the stack. The following algorithm will implement a queue using two stacks.

(1) When calling the enqueue method, simply push the elements into the stack 1.

(2) If the dequeue method is called, push all the elements from stack 1 into stack 2, which reverses the order of the elements. Now pop from stack 2.

Activate W

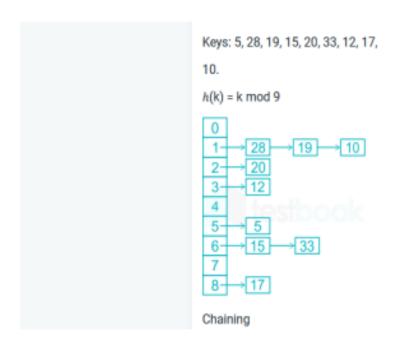
Solution steps

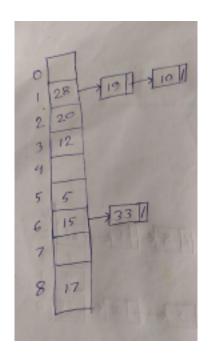
- 1. Take two stacks S1 and S2.
- 2. If S1 is empty, insert directly into S1.
- 3. If S1 is not empty, push all the elements from S1 to S2.
- 4. Push the element to be inserted into S1.
- 5. Push everything from S2 back to S1.

Chapter 11

2017-18 . 4.

i)Demonstrate what happens when we insert the keys 5,28,19,15,20,33,12,17,10 into a hash table with collisions resolved by chaining.Let the table have 9 slots, and let the hash function be $h(k)=k \mod 9$.

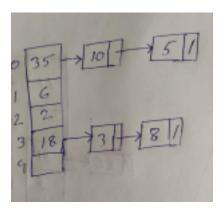




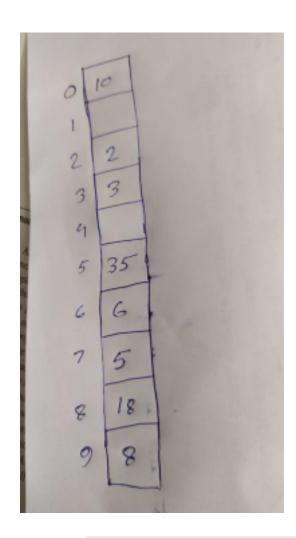
2016-17.

4.

i)Take an initially empty hash table with five slots, with hash function h(x)=x%5 and with collisions resolved by chaining .Draw a sketch of what happens when inserting the following sequence of keys into iy:35,2,18,6,3,10,8,5



ii)repeat part (a) but with the following changes; the hash table with ten slots , the function is h(x)=x%10 and collision resolved by linear probing.



Video link ■ 8.1 Hashing Techniques to Resolve Collision| Separate Chaining and Linear Pro...

Chapter 15

Same as Chapter 4

For a better understanding of TOH & LCS You can see the videos which I provide below:

For LCS: LCS - Longest Common Subsequence - Algorithms (Bangla Tutorial)

I Can't understand MCM (Matrix Chain Multiplication). Though it's not an important topic you should learn it!

I'm also unable to understand the LCS algorithm due to a lack of my time

Chapter 21 & 22 (V.V.I)

#নিচের প্রশ্ন সল্ভের সাথে টপিক মিলিয়ে ইউটিউবে ভিডিও দেখলেই বুঝা যাবে।

Topological sort using DFS:

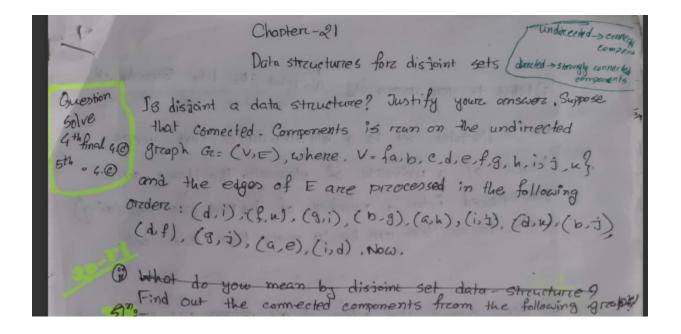
□ Topological sort using DFS | with starting time and finishing time | bangla

Strongly Connected Component:

- Connected and Strongly Connected Components in a Graph #Graph Series #24
- Strongly Connected Component

Types of edges:

■ 6.3 Types of Edges in DFS | Edge Classification | Data Structures and Algorithms



5779-	The connected components troom the following groups
Edge Proceed	
initial set	[63] 963 fc3 sd3 fe3 ff3 393 sh3 1183 53
(d,i)	183 963 963 93; 1 8e3 883 863 863 863 853 843
(f, u)	{aq pbg fel sd, is seg ff, kg fgg fhg fing sug
(3.1)	Pag 863 feg fdi. 93 feg 88,49 583 fn3 \$333347
(6,8)	(60) (b,di, 9) (C) Se? (b, u) for the fif fif ful
(a,h)	Pa, h? Pb.d.i. 89 se3 fe3 St, u3 saf flat Sig for Sh?
(i, i)	fa, h3 fb, d, i, 8, j} fe? fe? ff, h} fag & ftq
(d,x)	Fa,43 Sb,d,i,g,j,f,K3 fc3 fe3.
(b,i)	Pa, h) {b,d,i,8,j,f,kg {ch {e}}
(d, f)	Sa, h ? b, d, i, 8, j, f, k ? {e} {e}
(i,e)	fa, 43 (b,d,t,g,t,f,k) fe3 Se3
(a,e)	Parties Sb. d. i, g. +, f. kg {e3
(i,d)	fah, of fb, d, i, 8, i, f, 43 fc3
So, the con	meeted components that we left with fache g, floding, is, 1, 1, 1, 2, and fo?

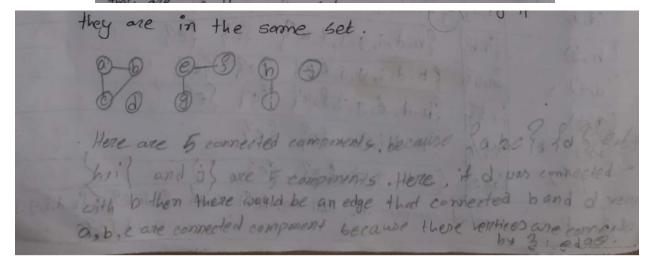
(i) What do you mean by dissoint get data strencture?

A disjoint set is a data strencture that neeps.

track of a universe of elements. The items are Paratitioned into a number of disjoint (non-overlaping sets, so no item can be in more than one set.

Also prove that offer all edges are processed by Connected-Components, two vertices are in the same connected component if & only if they are;

If two vertices are not in the same set, meaning that no edge connecting the set of one vertice with the others. So two servertices are in the same connected component if and only if



Durling the execution of Connected-Components on the or undirected graph .Gz = (V, E) with k connected components, how many times is Find-Set called? How many times is Union-set called? Express answer in terms of [V], |E] and k.

Find set is called twice on line 4, this is run once percedge in the graph, so, we have that find set in trum 2/EI times. Since, we staret with IV/sets, at the end only have k, and each call to UNION reduces the number of sets by one, we have that we have to of made [V]-k cally to UNION.

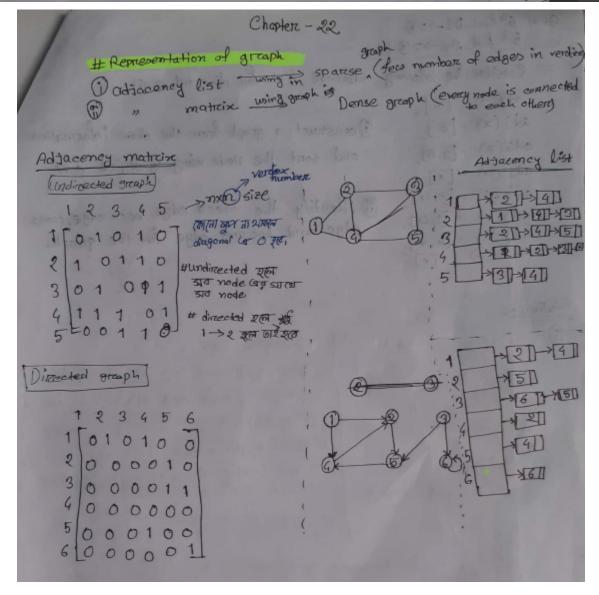
4.00	Disjoint set collection using 00000
Edge processed	collection of disjoint sets 9 0
initial sets	fa 3 fb ? fc ? fd ? fe ? ff ? fg ? \$13 \$13 \$13 \$1
(O1, b)	fab? {c} {d} feq ffqqqqqqqqqqqqqqqqqqqqqqqqqqqqqqqq
(a,c)	{a,b,c} {d? {eq ft? 383 €h?? 3539
(6,0)	fab.e? fd98e88f38038h382355
(e,f)	fable3 fd3 fest3, fo3. fh3fi7f57
(e, g)	fa,b,c9 fd3 fest, 83 fh3fi3fis
(h, i)	Banc3 fd3 fe.f.83 (h.i) 137
So the con	meeted components that we left, fab. of false 183. Swi3953

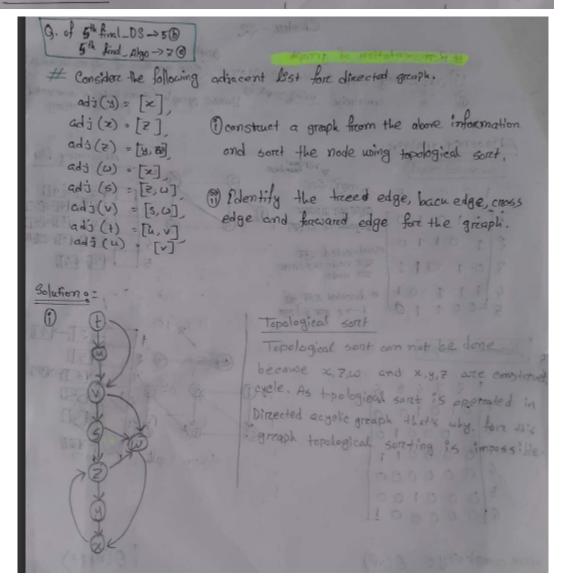
5th final DS

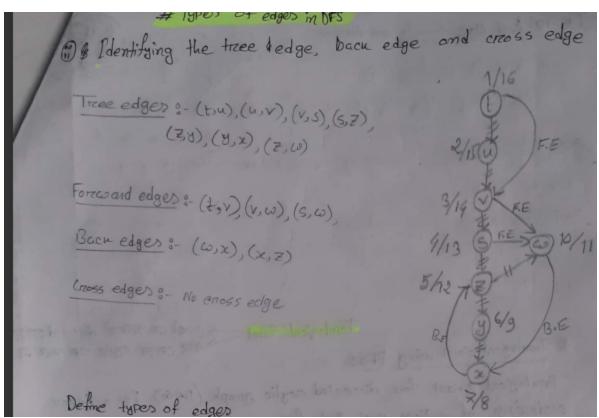
4. @ What is the rounning time of BF3 if we represent its input graph by an adjacency matrix and modify the algorithm to handle to handle this form of input?

If we use an adjacency matrix for each vertex u and we decide will be a promine all vertices to be decide whether

If we use an adjacency matrix for each vertex u and we deque well have to examine all vertices v to decide whether or not v is adjacent to u. This moves the fore-loop of line 12 0(v). In a connected graph we enqueue every vertex of the graph, so the workst case rountime becomes $O(v^2)$







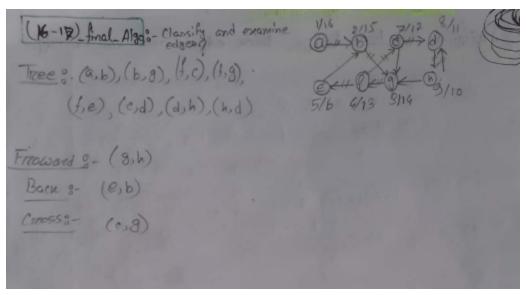
Define types of edges

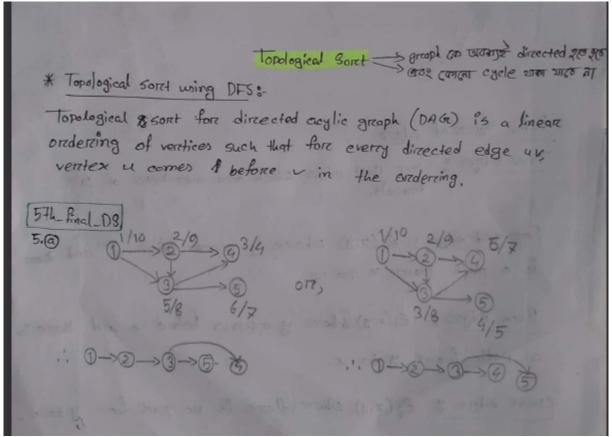
Tree edges: Are that edges which are members of DFS
travels.

Foreward edges: e:(x,y) where y appears after x and there
is a path from x to y.

Back edges? e:(x,y) where y appears before z and there is
a path from y to x.

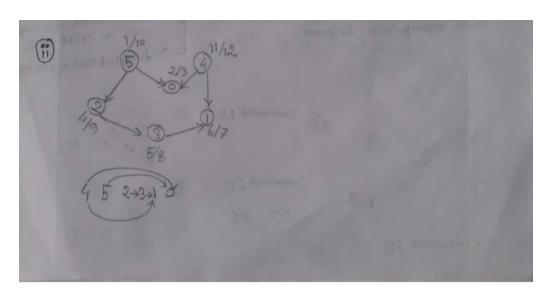
Ctross edge g e:(x,y) where there is no path from y to x.





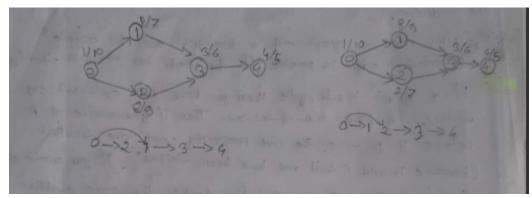
14th final_DS

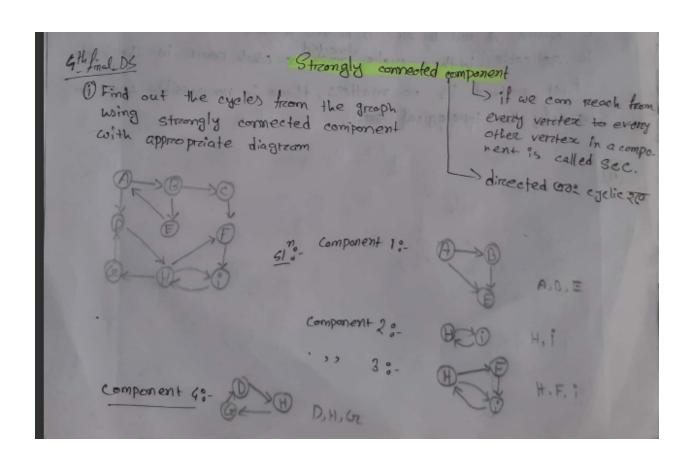
X. D A Topological sort orz topological ordering of a directed graph is a linear ordering of its vertices such that for every directed edge u and v from vertex u to vertex v, u comes before v in the ordering.

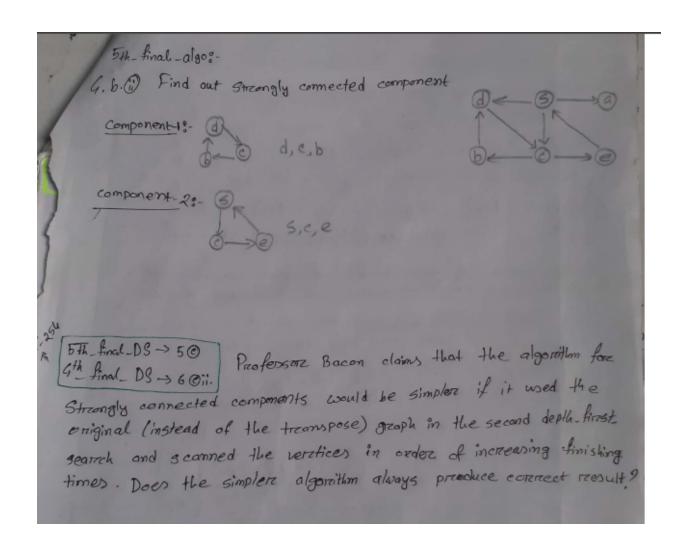


Scanned with CamScanner

7.0 A topological sort or topological ordering of a directed graph is a linear ordering of its vertices wis such that for every edge, u and v from vertex u to vertex v, u comes before v in circlering of find out the topological sort







Chapter 23

প্রশ্ন সল্ভ না বুঝাটাই স্বাভাবিক। তাই মেইন বই বা এই টপিকের ভিডিও দেখে প্রশ্ন সল্ভ করলেই ইজিলি বুঝতে পারার কথা।

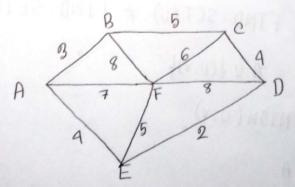
batch (2nd Semi) 2nd mid

krouskal's algorathm:

- 1. Graph review 100p. multiple edge delete 2000 2001.
- graph কোন eyele ছণ্ডয়া মাপ
- 3. तपुत्र graph ventex रूप अल्बा किएमा graph ventex signa (ant edge Re (ventex-1) avention?

avention;

1) Find the minimum weight for the minimum spanning tree and highlighted the selected nodes and edges.



To find the minimum weight of minimum spaning tree. we use krookal algorithm's.

MST-krookal (G.W)

1. A = 0

2. for each vertex v ∈ G.V

3. Make-SET (v)

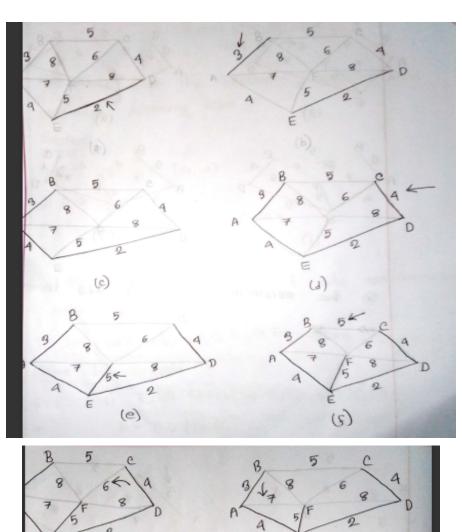
4. sort the edge of G.E into non-directreasing order by weight w

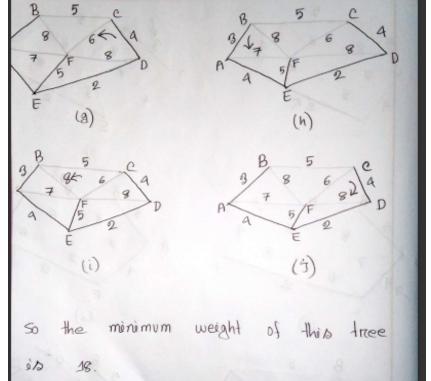
5. for each edge (u,v) ∈ G.E taken non-decreasing

- 6. of FIND-SET(U) = FIND-SET(V)
- 7. A = A U {(U,V)}
- (v.v) MOINU 8

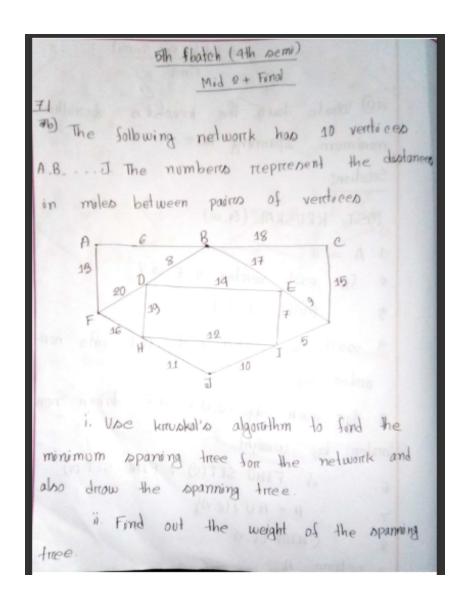
order by weight

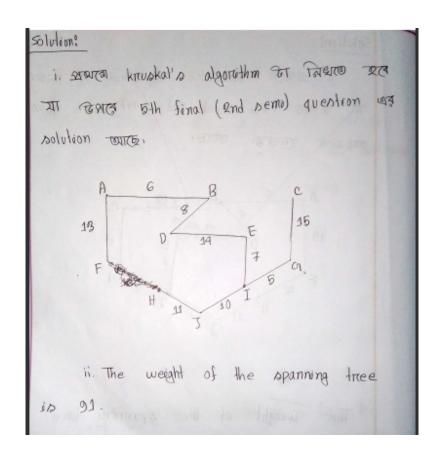
9. neturn A





5th balch (2nd-Semi) Final 80 Write down the daoridhm kruskal's spanning tree. minimum Solutions MST- KRUSKAL (G,W) 2. for each vertex V E G.V MAKE - SET (V) a sort the edges a of G.E into non-decraping orden by weight w 5. for each edge (U.V) & Cr.E taken non-decreasing by weight. Order if FIND-SET (v) = FIND-SET (v) A = AU { (U.V)} (V.U) NOENU 9. return A





1th batch (31d semi) Final

De A minimum spanning tree (MST) on minimum weight spanning tree is a subset of the edges. Of a connected edge-weighted (un) directed graph. That connects all the vertices together, without any eyeles and with the minimum possible total edge weight.

i) Describe in detail both prom's and kruskal's algorithms for finding a minimum cost spanning thee of an undirected graph with edges labelled with positive costs and explain why they are cornect.

ii) compare the relative merets of the

Sow lutions (

Prain's algorathm starts with the single node and explore all the adjacent nodes with all the connecting edges at every step. The edges with the minimal weights causing no eyeles in the graph got selected.

```
MST-PRIM (G, W, \pi)

1. fo\pi each u \in G, V

2. u \cdot key = \infty

3. u \cdot \pi = NIL

4. \pi \cdot key = 0

5. d = G, V

6. while 0 \neq 0

7. u = EXTRACT-MIN(0)

8. fo\pi each v \in G. Adj[u]

9. if v \in Q and u(v, v) < v \cdot key

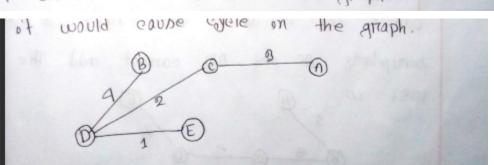
10. v \in V, \pi = U
```

11. v.key = w(v, v)

For example construet MST for the following

Arraph. B 10 0 3 A

choose a starting vertex B. choose the edge with the minimum weight among all i.e. BD and Add to the MST. Add the adjacent vertices of D i.e c and E. DE and CD edge are add to MST because they are minimum weighted edge. Then choose CA. We cannot choose CE because it would cause eyele in the graph.



Makruskal's algorathm's: kroupkal's algorathm वद्याद्य 5th batch (2nd sem) क्याट्ट , question augus construct For example greaph this edge because MIST add AB to the BDE and BC and also is minimum. Then add The next step is to add AE add it as it will eause add. The Ac and AD cannot somo pilarly MST in

Prain's algorithm is significantly faster in the limit when we have got a really dense graph with many more edges than vertices. But the knowled performs better in typical situations (sparse graphs) because it uses simpler data structures. The knowled algorithm is better to use regarding the easier implementation and the best control over the resulting MST.

3rd batch (4th semi) Final

Al a.b > same acquestion + answer 5th batch (4th semi) final + mid 2 197 a.b.

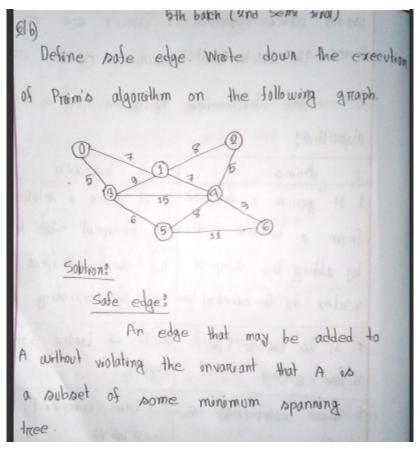
What is prain's algorathm? Identify it's difference with krouskal's algorathm.

Solution:

Promis algorithm's

Pram's algorathm used find minimum spanning tree from a Prim's algorithm finds the graph edges that includes every vertex graph the weights Duch that the DUM 07 of be minimized. edges can

	between prim's and knushali
Prainis	kruskal's
from a trandom vertlex by adding the cheapent	1. It grows a solution from the cheapest edge by adding the next cheapest edge to the existing tree.
e. It is foster for dense graphs.	2. It is footer for sparse
3. Time complexity is	3. Time complexity on O(E log V)
 The traverise one node more than one time to get minimum 	a. It traversse one node only once



```
MST. PRIM (G.w.R)

1 SOR each u \in G.V

2. u. key = \infty

3. u. \pi = NIL

4. \pi.key = 0

5. g = G.V

6. while g \neq 0

7. u = EXTRACT-Min(g)

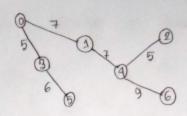
8. Sore each v \in G.Ad_T(v)

9. if v \in R and w(v,v) < v.key

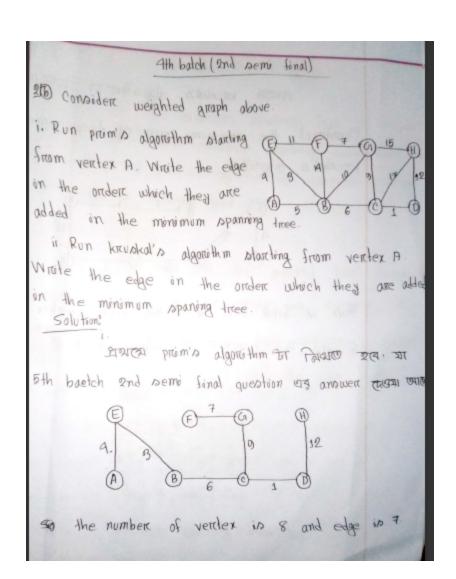
10. v. \pi = v

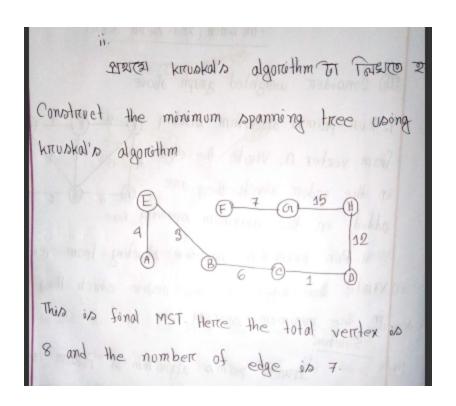
11. v. key = w(u.v)

Apply the prim's algorithm for the follow graphs
```



choose a storting ventex 0 choose the edge with the minimum weight among all 0 i.e 03 and and add to the MST Add the adjancy ventices of 3 i.e. 1.5. Add 35 to the MST and this edge is minimum weight. Then choose 01 and 14 and add them to the MST. Add the adjancy ventices of 4 add 42 to the MST. The next step is to add 21 but we connit add it to the MST because it will cause cycle similarly we cannot add 45 and 13. Now add 46 to the MST. This





5th batch (2nd nems) Mid-2

20 Show that the minimum spanning tree is unique but the second-best minimum spanning tree need not be unique and give an abportion to compute second best minimum spanning tree.

Solution?

To see that the second best minimum spanning tree is not be unique, we consider the following example graph on four vertices suppose the vertices are {a,b,c,d} and the edge weights are as follows:

	10	16	0	di
a	-	1	9	3
b	1	-	5	2
C	4	5	1-	6
d	3	2	6	-

Then the minimum spanning tree has weight 7 but

there are two spanning trees of second best weight 8.

We provide here an algorithm that takes time $O(v^2)$ and leave open if there exists a linear time solution, that is a O(E+v) time solution. First we find a minimum spanning tree in time O(E+v|g(v)), which is in $O(v^2)$. Then using the algorithm, we find the double array max. Then we take a rounning minimum

Over all pairs of verdices u, v of the value of w(u,v) - max [u,v]. If there is no edge between u and v, we think of the weight being infinite. Then son the pair that resulted in the minimum value of this difference, we add in that edge and remove sroom the minimum spanning trees

an edge that is t in the path from utov that has weight max [u,v]

Chapter 32

Naive string matching:

■ Naive String Matching Algorithm in Hindi with Solved Examples - Algorithm Design Analysi...

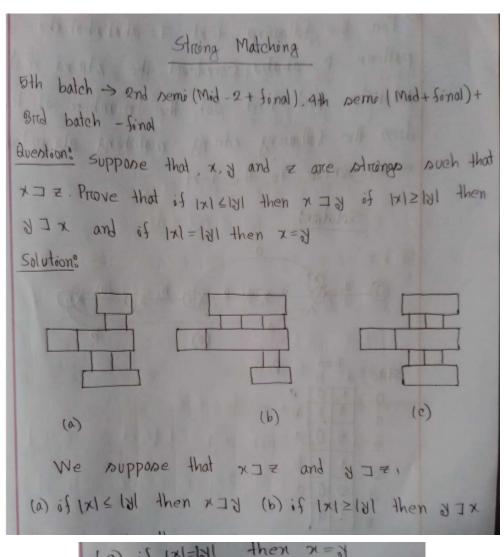
Finite automata: ai video tar 24 min theke dekbi

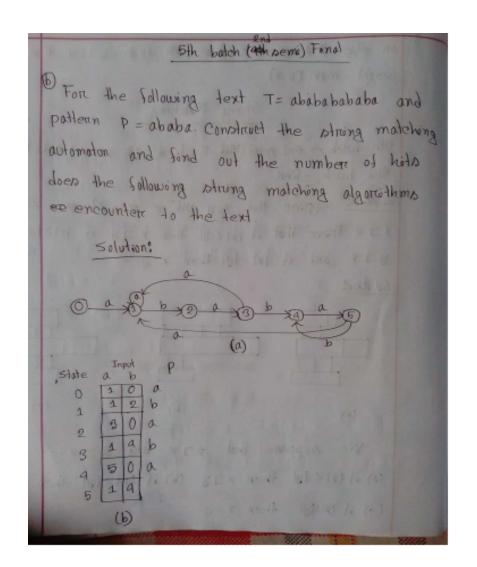
DAA96: Algorithm for String Matching with Finite Automata | Finite Automata String Matching

Aita dekbi table ta kivabe create kre tar jonno

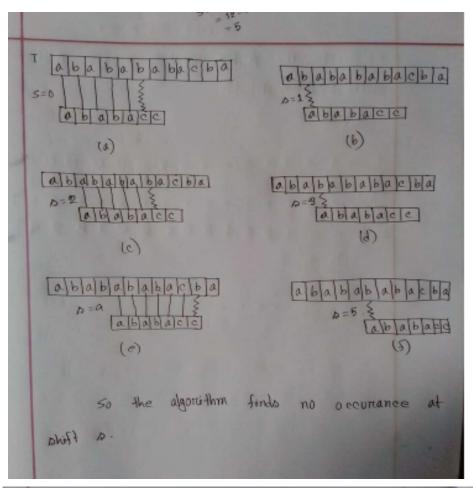
String Pattern Matching with Finite Automata||Example-1||Design and analysis of algo...

Compute Pi function: kmp algorithm prefix function shortcut method | kmp algorithm in daa





5th batch (ath semi) Final 21 a) Wrote down the number of hits does the following string matching algorithms execurter in the text P = ababababacba, pattern P = ababace and also wrote down their procedure. i. Naive strong Matching ii. Finate Stale Automata Solution: O NAIVE STRING MATCHER (T.P) 1 n = T. length 2 m = P length 3 for s = 0 to n-m. 4 if p[1 m] = T [s+1 s+m] 5 prent Pattern occurs with shift or



Compute the prefix Sunction * for the pattern ababbabbabbabbabb.

Solution.

i -> 1 2 3 4 5 6 7 8 9 30 31 12 13 14 15 16 17 28 11

T[i] a b a b a b b a b b a b b a b b a b b a b b a b a b b a b a b b a b a b b a b a b b a b a b b a b a b b a b a b b a b a b b a b a b b a b a b b a b a b b a b a b b a b a b b a b a b b a b a b b a b a b b a b a b a b b a b a b a b a b a b a b a b a b a b a b b a b